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Total No. of Pages : 02

Total No. of Questions : 09

B.Tech.(AE) (2011 Onwards) (Sem.-6)

VEHICLE DYNAMICS

Subject Code : BTAE-603

Paper ID : [A2382]

Time : 3 Hrs.

Max. Marks : 60

INSTRUCTION TO CANDIDATES :

1. SECTION-A is **COMPULSORY** consisting of **TEN** questions carrying **TWO** marks each.
2. SECTION-B contains **FIVE** questions carrying **FIVE** marks each and students have to attempt any **FOUR** questions.
3. SECTION-C contains **THREE** questions carrying **TEN** marks each and students have to attempt any **TWO** questions.
4. Assume any missing data suitably.

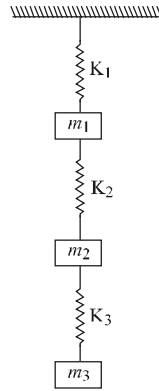
SECTION-A**1. Write briefly :**

- a) What is meant by magnification factor?
- b) Define transmissibility.
- c) Is there any difference between Eigen value and natural frequency? Explain.
- d) What is meant by wheel whop?
- e) What is meant by rigid mode of vibration?
- f) What is modal analysis?
- g) What are various cornering forces?
- h) What is meant by characteristic speed?
- i) What is meant by roll center?
- j) What is meant by a banked road?

SECTION-B

- Compare free and forced vibrations based upon inputs and outputs of the vibrating system.
- Estimate the fundamental frequency of vibration of a system shown in figure below.

Assume that $m_1 = m_2 = m_3 = m$; $k_1 = k_2 = k_3 = k$ and the mode shape is $X = \begin{Bmatrix} 1 \\ 2 \\ 3 \end{Bmatrix}$.



- Explain the factors influencing the choice of suspension spring rate.
- Describe the ride characteristics of tyre.
- Differentiate between low speed turning and high speed turning.

SECTION-C

- Calculate the pitch and bounce centers and their frequencies for a car with following characteristics :

Front ride rate = 127 lb/in

Front tire load = 957 lb

Rear ride rate = 92.3 lb/in

Rear tire load = 730 lb

Wheelbase = 100.6 in

Dynamic Index = 1.1

- Determine the eigen values and eigenvectors of a vibrating system given by

$$m = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{and} \quad k = \begin{bmatrix} 1 & -2 & 1 \\ -2 & 4 & -2 \\ 1 & -2 & 1 \end{bmatrix}$$

- Write a detailed note on stability of a vehicle on a slope and on a curve.